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Terminal Settling Velocity of Cylindrical Rods of Various Shapes

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Abstract - In this research, a set of straight, curved, V-shaped, and U-shaped cylindrical rods are dropped in a chamber filled with a quiescent glycerin mixture to approximate the settling of microplastic fibres in the environment. The fall trajectory and terminal velocity of the rods are determined using cameras facing the two perpendicular sides of the chamber. The results show that the terminal velocities of the curved and V-shaped rods are greater than those of the straight rods with the same diameter and aspect ratio. U-shaped rods always exhibit a greater terminal velocity than straight rods with the same dimensions. As the aspect ratio of a U-shaped rod increases, the terminal velocity initially increases, reaches a peak value, and then decreases, reflecting the interplay between the length of the rod arms and the inclination angle. This research shows that fibre shape significantly affects the terminal velocity, which must, therefore, be included in future non-dimensional models to accurately predict the transport of microfibres in the environment.

Keywords: Microplastics; Microfibres; Settling Velocity; Particle; Environment.

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1. Introduction

Microplastics (MPs) are a subset of plastics with sizes ranging between 1 µm and 5 mm [1-3]. MP pollution is known to spread through the environment, span the globe from urban to remote areas [4-7], and pose risks to human health and ecosystems. For instance, inhaling MPs can lead to respiratory illnesses [8-10]. These particles may also contain components and additives which can harm human health when inhaled or ingested [11, 12]. Their presence in ecosystems raises concerns about food safety and potential health issues [13]. Furthermore, MPs in Arctic glaciers can absorb sunlight, reducing the ice surface albedo and accelerating ice melting [14, 15]. Of reported atmospheric deposition samples, fibres are a prevalent shape, and often the most abundant [2, 5, 16, 17]. Past efforts to model the atmospheric transport of microplastic fibres (MFs) have usually relied on simplified representations of shapes such as spheres or a single straight fibre to estimate properties such as terminal velocity [6, 18, 19]. In the present research, the settling of rigid cylindrical rods of various finite lengths and shapes is studied to better understand how size and shape can affect the terminal velocity of microfibres. This is important in atmospheric transport studies, such as that of Ward et al. [20], where transport predictions of microplastics are sensitive to the size and shape of the particles modelled as equivalent spheres.

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Numerous aerodynamic models to estimate the terminal velocity of general non-spherical particles were reviewed by Michaelides and Feng [21]. At the core of modelling predictions is the particle size or shape representation. For example, Ganser [22] modelled the drag coefficient of isometric and nonisometric particles using a generalized Reynolds number, a function of Stoke's and Newton's shape factors, to predict the drag coefficient. In the study conducted by Song et al. [23], drop tests were performed using spheres, cubes, and cylinders of varying sizes and aspect ratios in glycerin mixtures with different viscosities. They introduced sphericity, indicating the ratio of the area of a volumeequivalent sphere to the particle area, and projected area ratio, indicating the ratio of the projected area of a volume-equivalent sphere to the particle projected area, to model their results. Bagheri and Bonadonna [24] conducted experiments in a vertical wind tunnel to determine the terminal velocity of a wide range of nonspherical particles. They modelled the drag coefficient of irregular particles utilizing the shape factors of flatness (the ratio of shortest length to intermediate length) and elongation (the ratio of intermediate to longest length). Zhang and Choi [25] modelled the terminal velocity of microplastic particles with the ability to differentiate between various shapes, including fibres, films, and fragments. Henn [26] proposed a theoretical correlation for the settling velocity of long cylindrical particles. When comparing the ratio of the aerodynamic equivalent diameter to the fibre diameter (given by D_a/D_c) with the experimental findings, their model exhibits a maximum discrepancy of 6% for glass fibre with aspect ratios between 5 and 150. Khalili and Liu [27] introduced an approach to estimating the drag coefficient of an infinite cylinder through the numerical analysis of the flow around the cylinder. Huner and Hussey [28] developed a drag coefficient model for an infinite circular cylinder within a Reynolds number range of 0.23 to 2.6, while Sen et al. [29] studied a uniform flow past a cylinder and provided a drag coefficient model applicable to Reynolds numbers between 6 and 40. However, when applied strictly to finite fibres of various shapes, these models all provide significantly varying results, and these results vary with Reynolds number. The recent work of the present authors provides a semi-empirical model to estimate the terminal velocity of both straight and curved cylindrical rods at Reynolds numbers applicable to microfibres in the atmosphere [30]. However, microfibres can take on a wider range of shapes.

Atmospheric deposition samples show that microplastic fibre shapes vary [2, 16, 31, 32], highlighting the question of geometry effects on settling behaviour. Concerning curvature, Rong et al. [33] found that curved fibres with a lower radius of curvature reach a faster terminal velocity terminal and achieve it more quickly with little overshoot compared to fibres with a larger radius of curvature. Yang et al. [34] also observed that curved fibres settle faster in their experiments. Nguyen et al. [35] found that larger curliness in fibre geometry leads to a lower terminal velocity, especially for fibres longer than 1 mm. Marchetti et al. [36] investigated the deformation of elastic fibres as they reach their terminal velocity. Their findings indicate that fibres may adopt a V shape under some conditions, while larger fibres can take on a U shape. Geometry or mass distribution asymmetry can also affect fibre orientation and terminal velocity. Roy et al. [37] demonstrated that fibres with an asymmetric distribution of radius or mass density experience a transition from a vertical to an oblique orientation as the Archimedes number increases or the degree of asymmetry decreases. A dumbbellshaped particle of two spheres connected by a weightless rod, studied by Candelier et al. [39], settles vertically when the spheres vary significantly with the larger at a lower position. However, as the size difference reduces, the orientation becomes obligue and horizontal when symmetric. Angle et al. [38] demonstrated that a cylinder with non-uniform mass distribution settles vertically at AR = 1 and slightly oblique at AR = 2 and 4. Where the cylinders adopted oblique orientations, they exhibited horizontal drift.

Many models that relate drag coefficients and Reynolds numbers for non-spherical geometries falling in air or liquid cannot accurately predict the terminal velocity of single straight fibres. Additionally, the effect of the shape of individual cylindrical rods on their terminal velocity at low Reynolds numbers is not yet extensively studied. In the present study, an experimental investigation is used to determine and compare the terminal velocities of cylindrical rods with four different geometries: straight, curved, V-shaped, and U-shaped. Our research aims to provide a deeper understanding of how various geometries affect the terminal velocity of microplastic fibres settling in the atmosphere. In this paper, Section 2 describes the experimental methods, test specimens, and equipment. Results on the terminal velocity are included in Section 3, followed by conclusions in Section 4.

2. Materials and Methods

The Reynolds number range (based on the diameter of a volume-equivalent sphere) associated with the microfibres settling in the atmosphere was predicted using the microfibre dimensions reported in the literature [5, 39-42] and the Henn model [26]. The calculations suggest that the Reynolds number is smaller than 5. Glycerin-water mixture with viscosities up to 1000 times as large as that of water enables us to use millimeter-scale metallic rods having Reynolds numbers less than 5 and makes it feasible to track the 3D fall trajectory and orientation of cylindrical rods. The straight, curved, V-shaped, and U-shaped cylindrical rods investigated in this research are all made of brass with a density of 8730±49 kg/m³ and have diameters (D_c) of 0.50, 0.81, and 1.0 mm (with an uncertainty of ± 0.05 mm) and aspect ratios (AR) varying from 10 to 120. The rods were cut with the mentioned aspect ratios with a tolerance of 0.1 mm. A schematic of the studied rods is shown in Figure 1. The radius of curvature (*ROC*) of the curved rods ranges from 19.90 mm to 36.40 mm, the bend angle (α) of the V-shaped rods varies between 45 and 135 degrees, and the length ratio of the middle arm (L_2) to the side arm (L_1) for the U-shaped rods is 1. The degree of curvature and bend for the curved and Vshaped rods respectively is denoted as C and defined as

$$C = 1 - \frac{L_P}{L_C} , \qquad (1)$$

where L_P is the projected length of the curved and V-shaped rods (shown in Figure 1) and L_C is the total length of the rod. Table 1 shows the dimensions of the rod geometries used in this study.



Figure 1: Schematic of the straight, curved, V-shaped, and Ushaped rods used in this research. L_c : total length of the rod, D_c : rod diameter, *ROC*: radius of curvature, α : bend angle, L_P : projected length, L_1 : the length of the U-shaped side arm, and L_2 : the length of the U-shaped middle arm.

The experiments are performed in a setup similar to that of Hamidi et al. [30]. Briefly described herein, two monochromatic cameras (Iron CXP 250) are positioned to face two perpendicular sides of the chamber, capturing the trajectory and orientation of cylindrical rods as they fall within the quiescent glycerin-water chamber. A third camera, under the tank, is used to observe the rotation of the falling rods. Rods are illuminated by two 10-watt LED lights with acrylic diffuser plates placed behind the chamber. The chamber is filled with a mixture of 90% glycerine and 10% water.

Table 1: The rod geometries studied in this research (Dc is
the rod diameter, AR is the rod aspect ratio, ROC is the radius
of curvature for curved rods, and $\boldsymbol{\alpha}$ is the bend angle for V-
shaped rods).

Geometry	Dc (mm)	AR	<i>ROC</i> (mm)	α (degrees)
Straight	0.50	10, 20, 30, 60, 90, 120		
	0.81	10, 20, 30, 40, 50, 60, 70, 90.		
	1.00	10, 20, 30, 45, 60		
Curved	0.50	60, 90	19.9, 27.3, 31.7, 36.4	
	1.00	30, 45	19.9, 27.3, 31.7, 36.4	
V-shaped	0.50	20, 30, 60, 90		45, 70, 90, 110, 135
U-shaped	0.50	30, 40, 50, 60, 90		
	0.81	30, 40, 50, 60, 90		

Error! Reference source not found. A Discovery HR-3 Hybrid Rheometer with a concentric cylinder geometry is used to measure the viscosity of this mixture with an uncertainty of 0.3%. The temperature of the mixture is monitored using a T-type thermocouple with an uncertainty of ± 0.1 °C. The glycerin mixture used in this research is a Newtonian fluid, meaning that its viscosity is independent of the shear rate and depends only on the fluid temperature. The settling of rods in non-Newtonian fluids can be studied in future research. MATLAB is used to analyse the images captured by the

cameras and a custom calibration algorithm is used to convert the pixel coordinates to real-life coordinates. The settling velocity of the rods is determined from the displacement of the rod centroid between two consecutive images and the time interval between frames. The terminal velocity is obtained when the tracked settling velocity shows random variations of less than 1% compared to the average velocity over the last 10 cm of its trajectory.

3. Results

The terminal velocities of the straight, curved, Vshaped, and U-shaped rods studied in this research are discussed in this section.

3.1. Straight Rods

The terminal velocities of the straight rods for the studied diameters and aspect ratios are plotted in Figure 2. This figure shows that as the diameter and aspect ratio of the rod increase, the rod terminal velocity increases. The rate of the change in the terminal velocity decreases with an increase in aspect ratio, leading to an asymptotic behaviour at high aspect ratios. For instance, for D_C = 0.81 mm, as the aspect ratio increases from 30 to 60, the terminal velocity increases by 4.3% (from 52.5 to 54.8 mm/s). However, the rod with an aspect ratio of 90, settling at 55.4 mm/s, settles only 1.2% faster than the rod with an aspect ratio of 60. This asymptotic trend also aligns with the findings from Javaweera and Mason [43]. The primary reason for this behaviour is the insignificant effects of the finite ends of the rod on the drag coefficient at high aspect ratios [30]. Furthermore, this figure compares the terminal velocity of the rod with $D_c = 0.5$ mm with the results of Song [23] and Henn [26] models. This comparison shows that the Song model [23] fails to accurately predict the terminal velocities of the rods within the ranges studied in this research since this model is developed for a wide range of particle geometries and consequently has lower accuracy for cylindrical particles. Henn model [26] aligns more closely with the experimental results obtained in this research. However, this model cannot still capture the asymptotic behaviour of the rod terminal velocity at high aspect ratios. The data points shown in Figure 2 are associated with a range of Reynolds numbers, which is calculated based on the diameter of the volumeequivalent sphere, between 0.07 and 1.75.



Figure 2: Terminal velocity of the straight rods for diameters of 0.50, 0.81, and 1.0 mm at different aspect ratios. The dashed and dash-dotted lines represent the Henn [26] and Song [23] models, respectively.

3.2. Curved Rods

Figure 3 illustrates the terminal velocities of the curved rods at different degrees of curvature ranging between 0.03 and 0.20 (refer to equation (1) and Figure 1) and compares them with those of the straight rods. It can be seen from this figure that the terminal velocity of a curved rod is always larger than that of a straight rod with the same diameter and aspect ratio. This can be attributed to the smaller projected area of the curved rods compared to the straight rods with the same dimensions. Furthermore, the streamlines of the flow around the rod can align better with a curved geometry compared to a straight one, resulting in a reduced drag coefficient [30, 33, 34]. As the degree of curvature of the rod increases, or in other words, as the radius of curvature decreases, the terminal velocity increases. For the selection of curved rods considered in this study, the terminal velocity of the curved rods is up to 17% more than the terminal velocity of the straight. At very low degrees of curvature, the rod geometry tends to resemble a straight geometry, and the terminal velocity of the curved rod approaches that of a straight rod with the same diameter and aspect ratio.



Figure 3: Terminal velocity of the curved rods at different degrees of curvature for two diameters of 0.50 and 1.0 mm and two aspect ratios of 60 and 90 as well as the straight rods with the same diameter and aspect ratio.

2.3. V-shaped Rods

Straight rods with a diameter of 0.50 mm were bent with angles of 45, 70, 90, 110, and 135 degrees to make V-shaped rods with degrees of bend ranging between 0.08 and 0.62. The terminal velocities of the Vshaped rods are plotted in Figure 4 at different degrees of bend. The results demonstrate that an increase in the degree of bend, corresponding to a decrease in the bend angle, results in a larger terminal velocity. The V-shaped rods always settle faster than the straight rods with the same diameter and aspect ratio. In addition to the smaller projected area of a V-shaped rod compared to a straight rod with the same dimensions, the V-shaped rod resembles two smaller rods connected to each other at an angle of α . Each smaller rod has an inclined orientation, resulting in a higher settling velocity compared to a straight rod, which has a completely horizontal orientation. Moreover, the calculations show a maximum increase of 57% in the terminal velocity of the V-shaped rods relative to the straight rods within the ranges studied in this research. Similar to the curved rods, the terminal velocity of a V-shaped rod asymptotes to that of a straight rod with the same dimensions at very low degrees of bending.



Figure 4: Terminal velocity of the V-shaped rods at different degrees of bend for the rod diameter of 0.50 mm and four aspect ratios of 20, 30, 60, and 90, as well as the straight rods with the same diameter and aspect ratio.

2.4. U-shaped Rods

Based on the observations, the U-shaped rods adopt an oblique orientation during their fall, leading to a horizontal drift in their trajectory. In this study, the orientation of the U-shaped rods is defined by the angle between the U-shaped side arm and the horizontal direction, as shown in Figure 5. This angle is referred to as the "inclination angle", and is denoted by θ .



Figure 5: A (a) side and (b) front view of the U-shaped rod. The angle between the side arm and the horizontal direction, denoted by θ , is called the inclination angle.

Figure 6 shows the variation of the U-shaped rod terminal velocity and inclination angle with the rod aspect ratio with all three arms equal ($L_1 = L_2$, L_1 and L_2 are represented in Figure 1). It can be seen from this figure that the terminal velocity of a U-shaped rod has a strong correlation with the inclination angle. For instance, for $D_c = 0.50$ mm, the inclination angle changes from 90 degrees (vertical orientation) to 40 degrees (oblique orientation) as the aspect ratio increases. This increases the terminal velocity from 33 to 38 mm/s and decreases from 38 to 35 mm/s as the aspect ratio increases. However, the rod terminal velocity remains almost constant with the change in the aspect ratio for D_c

= 0.81 mm since its inclination angle changes only from 37 to 25 degrees. The observed trends in the terminal velocity of the U-shaped rod as the aspect ratio increases can be explained by the interplay between the size and orientation of the rod. As the aspect ratio of the rod increases, the inclination angle decreases, and the rod aligns more horizontally, which leads to a decrease in the terminal velocity. However, the side arms of the Ushaped rod increase in length with the increased aspect ratio, increasing the terminal velocity. The mentioned counteracting factors cause the U-shaped rod to exhibit either an initial rise and a subsequent decrease in the terminal velocity (as observed for $D_c = 0.50$ mm) or an approximately constant value (as observed for $D_c = 0.81$ mm) as the aspect ratio increases. Furthermore, Figure 6 demonstrates that the terminal velocity of a U-shaped rod is always larger than a straight rod with the same diameter and aspect ratio due to the non-zero inclination of the U-shaped rods. The maximum difference between the U-shaped and the straight rod terminal velocity is approximately 40% in this study.



Figure 6: Variation of the (a) terminal velocity and (b) inclination angle of the U-shaped rods with aspect ratio. Figure (a) also compares the velocities of the U-shaped rods with straight rods.

4. Conclusions

The atmospheric settling of microplastic fibres is experimentally replicated by performing drop tests with straight, curved, V-shaped, and U-shaped cylindrical rods made of brass in a chamber filled with a quiescent glycerin-water mixture. The terminal velocity of the falling rods is determined by analysing the sequences of images captured from two cameras facing the two perpendicular sides of the chamber. The results indicate that the terminal velocity of a straight rod increases with the rod diameter and aspect ratio, showing an asymptotic behaviour towards a constant value at high aspect ratios, which is consistent with previous studies in the literature. Compared to straight rods, the curved and V-shaped rods with the same diameter and aspect ratio, i.e. the same rod but with various bent geometries, settle faster. The terminal velocity of the curved and the V-shaped rods increases with the degree of curvature and bend, which are associated with a decrease in the radius of curvature and bend angle for the curved and Vshaped rods, respectively. The terminal velocity of a Ushaped rod is determined by the trade-off between the length of its arms and the orientation of the rod. An increase in the aspect ratio of a U-shaped rod causes a decrease in its inclination angle and an increase in the length of the rod arms. This leads to the terminal velocity of the rod either first increasing and then decreasing or remaining constant as the rod aspect ratio increases. The terminal velocity of a U-shaped rod is consistently greater than that of a straight rod with the same diameter and aspect ratio. According to the results of this research, a general conclusion for rods of the same diameter and aspect ratio is as follows. V-shaped rods (or fibres) exhibit a higher vertical terminal velocity than Ushaped ones. The settling velocity of U-shaped rods (or fibres) exceeds that of curved ones, and curved geometries result in a terminal settling velocity that exceeds those of straight geometries. Given this difference in settling velocity, curved or bent microfibres may have a reduced transport distance by the atmosphere compared to straight fibres, depending on the degree of bend or curve.

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